

Lecture 6

$$\boxed{\frac{dv}{dt} = g - \frac{c_d}{m} v^2}$$

$v(0) = 0$

$$, \quad 0 < t \leq t_F$$

$$(*) \quad \frac{dv(t)}{dt} \approx \frac{v(t+h) - v(t)}{h} \quad \text{provided } h \text{ is small}$$

$$\rightarrow \quad t_0 = 0, \quad t_1 = \Delta t, \quad t_2 = 2\Delta t, \dots, \quad t_F = n \Delta t$$

Δt : time step

$$v_i = v(t_i)$$

from (*)

$$\boxed{\frac{dv}{dt}(t_i) \approx \frac{v(t_i + \Delta t) - v(t_i)}{\Delta t}} \quad (**)$$

from equation of v :

$$\frac{dv}{dt}(t_1) = g - c_d v(t_1)^2$$

$$\frac{dv}{dt}(t_2) = g - c_d v(t_2)^2$$

$$\frac{dv}{dt}(t_{n-1}) = g - c_d v(t_{n-1})^2$$

general i , $i = 1, 2, \dots, n-1$

$$v_i := v(t_i)$$

$$\frac{dv}{dt}(t_i) \approx \frac{v(t_i + \Delta t) - v(t_i)}{\Delta t} = g - \frac{c_d}{m} v(t_i)^2$$

$$\Rightarrow \frac{v_{i+1} - v_i}{\Delta t} = g - \frac{c_d}{m} v_i^2$$

$$\Rightarrow v_{i+1} = v_i + \Delta t \left(g - \frac{c_d}{m} v_i^2 \right)$$

✓ v_0

$$\checkmark v_1 = v_0 + \Delta t \left(g - \frac{c_d}{m} v_0^2 \right)$$

$$\checkmark v_2 = v_1 + \Delta t \left(g - \frac{c_d}{m} v_1^2 \right)$$

⋮
⋮

$$\checkmark v_n = v_{n-1} + \Delta t \left(g - \frac{c_d}{m} v_{n-1}^2 \right)$$

$$v(t_i) = v_0$$

for $i = 2 : n$

$$v(i) = v(i-1)$$

$$+ \Delta t \left(g - \frac{c_d}{m} v(i-1)^2 \right)$$

end

Errors in Numerical simulation

- X (i) finite capacity of computers in representing numbers
- ✓ (ii) discretization error, truncation error, numerical errors
- ✓, X (iii) modeling errors

E. P. Bon \Rightarrow "All models are wrong, but some are useful"

- X (iv) uncertainty/observation error/experimental error in data
- ✓ (v) wrong numerical implementation

Precision : $a_i, \quad i=1, \dots, n$

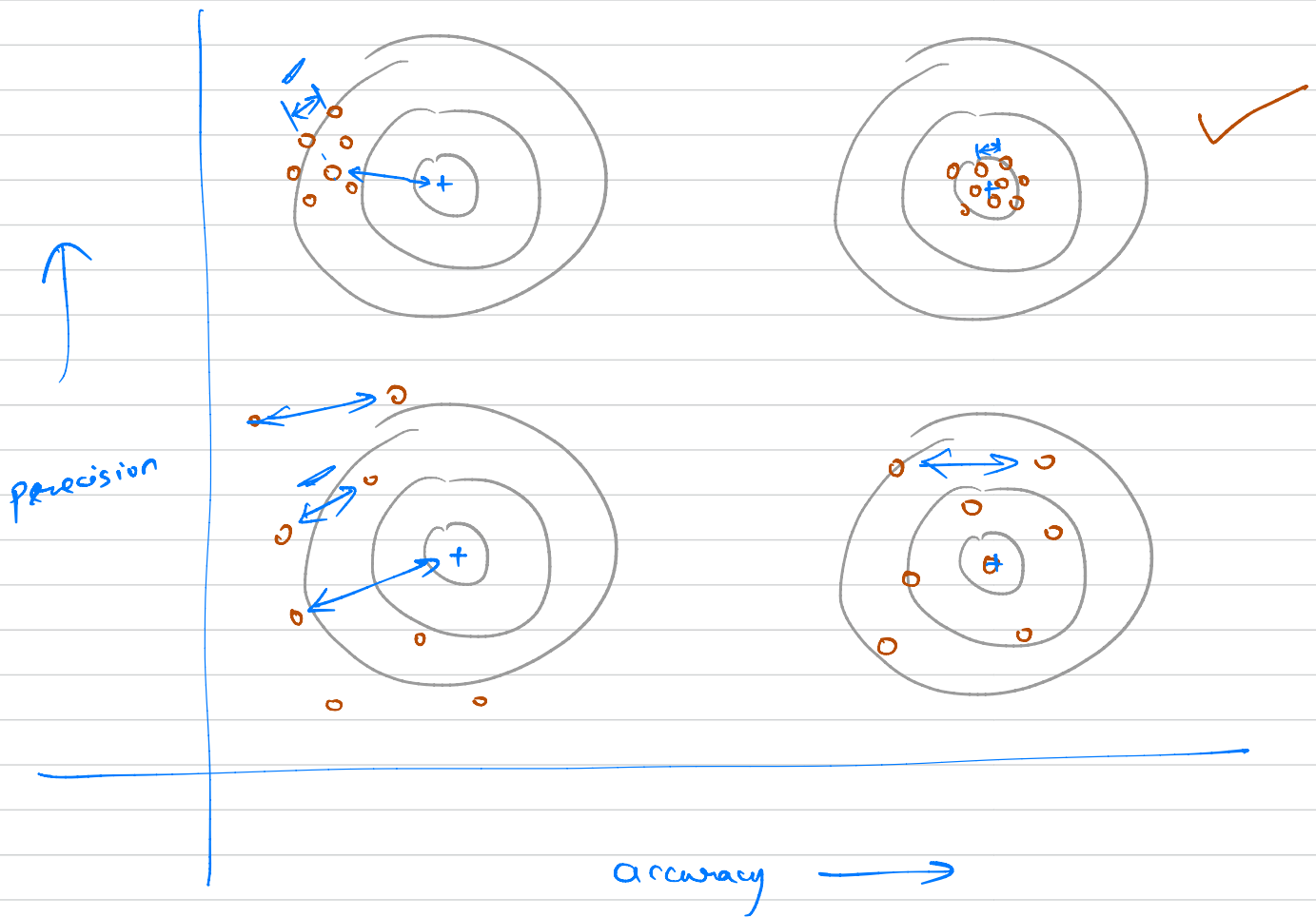
$$|a_2 - a_1| > |a_3 - a_2| > \dots > |a_n - a_{n-1}|$$

Accuracy : if suppose, I know true value a ,

then

$$a - a_i$$

$$|a - a_1| > |a - a_2| > \dots > |a - a_n|$$
$$< \qquad \qquad \qquad < \dots <$$



Definition of error:

True error: Applicable only if you know the true value

$$E_t = (\text{True value} - \text{Approximate value})$$

$$v_{\text{true}} = 10 \text{ m/s}$$

$$v_{\text{app}} = 9 \text{ m/s}$$

$$E_t = 1 \text{ m/s}$$

$$v_{\text{true}} = 10000 \text{ m/s}$$

$$v_{\text{app}} = 9999 \text{ m/s}$$

$$E_t = 1 \text{ m/s}$$

$$e_t = \frac{E_t}{\text{True value}} \times 100 \%$$

$$e_t = 10\%$$

$$e_t = 0.01 \%$$

$$E_a = \frac{\text{Present approximate value} - \text{Previous approximate value}}{\text{Present approx. val.}} \times 100\%$$

$$N(t_F; \Delta t)$$

$$N(t_F; \Delta t/2)$$

$$N(t_F; \Delta t/4) \dots N(t_F; \frac{\Delta t}{2^n})$$

$$\frac{N(t_F; \Delta t/2) - N(t_F; \Delta t)}{N(t_F; \Delta t/2)}$$

$$\frac{N(t_F; \Delta t/4) - N(t_F; \Delta t/2)}{N(t_F; \Delta t/4)}$$

$$\frac{N(t_F; \frac{\Delta t}{2^n}) - N(t_F; \frac{\Delta t}{2^{n-1}})}{N(t_F; \frac{\Delta t}{2^n})}$$

$x \in [x_1, x_2]$

$f(y), f'(y), f''(y), \dots$

$$f(x) = f(y) + f'(y)(y-x) + \frac{1}{2!} f''(y)(y-x)^2$$

$\xi \in [x_1, x_2]$

$$+ \frac{1}{3!} f'''(\xi)(y-x)^3$$

$$f'(y) = \frac{df}{dy}, \quad f''(y) = \frac{d^2f}{dy^2}, \quad f'''(y) = \frac{d^3f}{dy^3}$$

$$f(x) = f(y) + \frac{f^{(1)}(y)}{1!} (y-x) + \frac{f^{(2)}(y)}{2!} (y-x)^2$$
$$+ \dots + \frac{f^{(n)}(y)}{n!} (y-x)^n + \dots$$