

Lecture 40

- Linear regression in one-dimensional setting

$\Rightarrow (x^1, y^1), (x^2, y^2), \dots, (x^n, y^n)$ n-pairs of data

x^i = independent variable (parameter) associated to data y^i

\Rightarrow find a model $\hat{y} = \hat{y}(x)$ for the data

↑
is scalar hence \hat{y} is one-dimensional function

\Rightarrow linear regression

$$\hat{y}(x) = z(x) \alpha$$

where $z(x) = [z_1(x), z_2(x), \dots, z_m(x)] \leftarrow \text{"known"}$

$$\alpha = \begin{bmatrix} \alpha_1 \\ \alpha_2 \\ \vdots \\ \alpha_m \end{bmatrix} \leftarrow \text{"unknown"}$$

Example: (i) $m=2$ and \hat{y} to be line

$$z(x) = [1, x]$$

(ii) $m=2$ and \hat{y} to be quadratic function

$$z(x) = [1, x, x^2]$$

(iii) $m=3$ and \hat{y} to be cubic function

$$z(x) = [1, x, x^2, x^3]$$

(iv) $m=3$ and \hat{y} to be exponential-like function

$$z(x) = [\exp[\lambda_1 x], \exp[\lambda_2 x], \exp[\lambda_3 x]]$$

and $\lambda_1, \lambda_2, \lambda_3$ are "known" and "fixed"

$$\lambda_1 \neq \lambda_2 \neq \lambda_3$$

(v) $m=4$ and \hat{y} to be sinusoidal-like function

$$z(x) = [\sin(w_1 x), \sin(w_2 x), \sin(w_3 x), \sin(w_4 x)]$$

w_1, w_2, w_3, w_4 are "known" and "fixed"

$$w_1 \neq w_2 \neq w_3 \neq w_4$$

Solving linear regression

- Error = squared error

$$E = E(a) = \frac{1}{n} \sum_{i=1}^n (y^i - \hat{y}(x^i))^2$$

- Problem:

find "a" such that $E(a)$ is minimum



this is
shown
in Lecture

$$Ja = b$$

where

$$J = \mathbf{B}^T \mathbf{B} \longrightarrow m \times m \text{ matrix}$$

$$\mathbf{b} = \mathbf{B}^T \begin{bmatrix} \mathbf{y}^1 \\ \mathbf{y}^2 \\ \vdots \\ \mathbf{y}^n \end{bmatrix} = \mathbf{B}^T \mathbf{J} \longrightarrow m \times 1 \text{ vector}$$

$$\mathbf{B} = \begin{bmatrix} \dots & z(x^1) & \dots \\ \dots & z(x^2) & \dots \\ \vdots & & \\ \dots & z(x^n) & \dots \end{bmatrix} \longrightarrow n \times m \text{ matrix}$$

$$= \begin{bmatrix} z_1(x^1) & z_2(x^1) & \dots & z_m(x^1) \\ z_1(x^2) & z_2(x^2) & \dots & z_m(x^2) \\ \vdots & & & \\ z_1(x^n) & z_2(x^n) & \dots & z_m(x^n) \end{bmatrix}$$

linear regression in multiple dimensional setting

Data: temperature at different points on plate

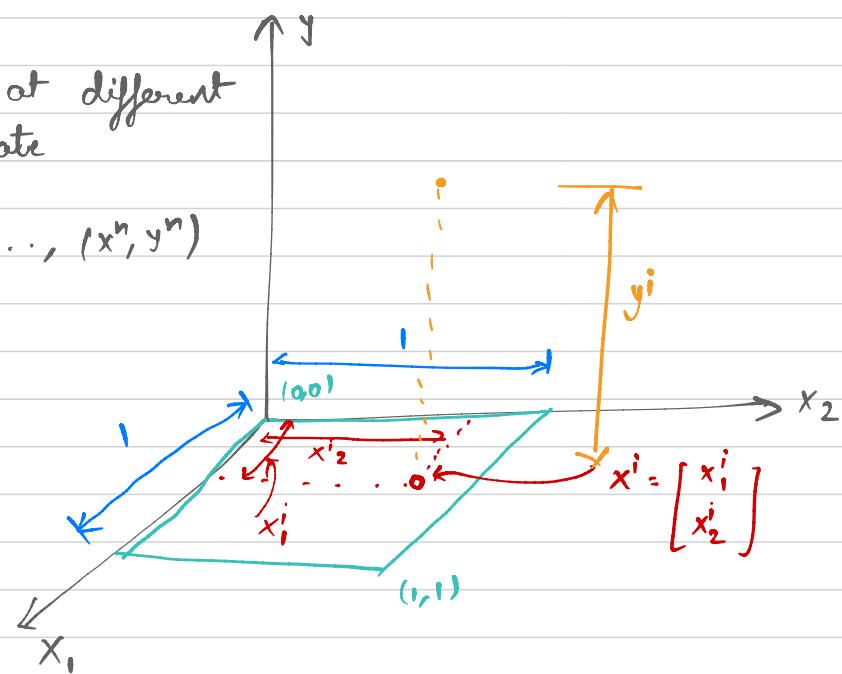
$$(x^1, y^1), (x^2, y^2), \dots, (x^n, y^n)$$

for i^{th} data

y^i = temperature at point x^i

x^i = coordinate of i^{th} point

$$= \begin{bmatrix} x_1^i \\ x_2^i \end{bmatrix}$$



Goal: find a model $\hat{y} = \hat{y}(x)$ for temperature data



x is a vector of two elements

& hence \hat{y} is a multi-dimensional function

Linear regression and using linear function, model \hat{y}

can be written as

$$\hat{y}(x) = a_1 + a_2 x_1 + a_3 x_2$$

$$= z(x) a$$

$$z(x) = [1, x_1, x_2], \quad a = \begin{bmatrix} a_1 \\ a_2 \\ a_3 \end{bmatrix}$$

using least square method, we have

"problem" find a s.t. $E(a) = \frac{1}{n} \sum_{i=1}^n (y_i - \hat{y}(x_i))^2$
is minimum



find a s.t. $J a = b$

where

$$J = B^T B, \quad b = B^T y, \quad y = \begin{bmatrix} y^1 \\ y^2 \\ \vdots \\ y^n \end{bmatrix}$$

$$B = \begin{bmatrix} \text{--- } z(x^1) \text{ ---} \\ \text{--- } z(x^2) \text{ ---} \\ \vdots \\ \text{--- } z(x^n) \text{ ---} \end{bmatrix}$$

$$= \begin{bmatrix} 1 & x_1^1 & x_2^1 \\ 1 & x_1^2 & x_2^2 \\ 1 & x_1^3 & x_2^3 \\ \vdots & \vdots & \vdots \\ i & x_1^n & x_2^n \end{bmatrix}$$

Linear regression using linear function in K-dimension

$(x^1, y^1), (x^2, y^2), \dots, (x^n, y^n)$ n-data set

for each i

$$x^i = \begin{bmatrix} x_1^i \\ x_2^i \\ \vdots \\ x_K^i \end{bmatrix}$$

model

$$\hat{y}(x) = a_1 + a_2 x_1 + a_3 x_2 + \dots + a_{K+1} x_K$$

$$= z(x) a$$

$$z(x) = [1, x_1, x_2, \dots, x_K]$$

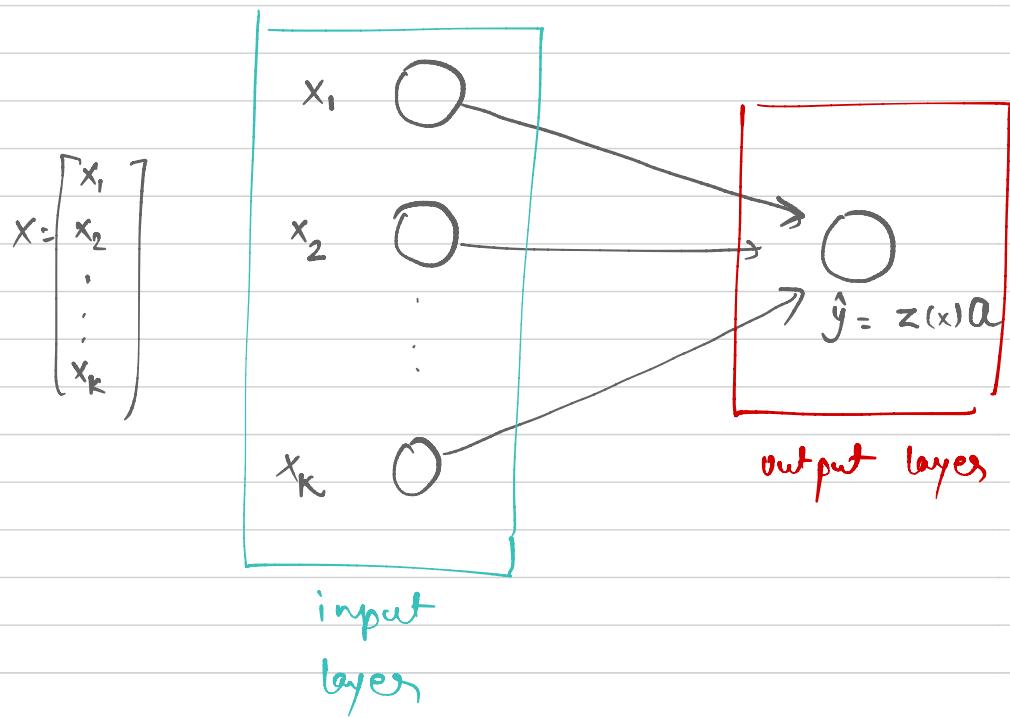
$$a = \begin{bmatrix} a_1 \\ a_2 \\ \vdots \\ a_{K+1} \end{bmatrix}$$

\Rightarrow Solve $J \alpha = b$ (equivalent to minimizing squared error)

$$J = B^T B, \quad b = B^T y, \quad y = \begin{bmatrix} y^1 \\ y^2 \\ \vdots \\ y^n \end{bmatrix}$$

$$B = \begin{bmatrix} 1 & x_1^1 & x_2^1 & \dots & x_K^1 \\ 1 & x_1^2 & x_2^2 & \dots & x_K^2 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & x_1^n & x_2^n & \dots & x_K^n \end{bmatrix}$$

Graphical representation of linear regression in k-dimension



- Nonlinear relation between input x and output y

$$x, \hat{y} = f(x; \theta)$$

↑ ↑
input are model parameters

$$= f^{(3)} \left(f^{(2)} \left(f^{(1)}(x; \theta^{(1)}) ; \theta^{(2)} \right) ; \theta^{(3)} \right)$$

$$\boxed{f^{(3)} \circ f^{(2)} \circ f^{(1)} \circ \text{id}(x) = \hat{y}}$$

